Designing Surprise Bags for Surplus Foods

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- Joint work with Fan Zhou (UMich \rightarrow CUHK-SZ), Andrea Li (Industry/TGTG), Joline Uichanco (UMich)

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Source: rednote





potentially **mitigating** it



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Stores



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Trash



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Emerging platforms across the world to combat food waste at stores by connecting



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Surprise Bags

Viral social media influence



Source: Tiktok



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Too Good To Go

"

Users purchase Surprise Bags filled with a mix of surplus food items.

We know that food waste varies on a dayto-day basis, so this is our way of making sure retailers have the flexibility to sell genuine surplus - whatever that ends up being.

Surprise Bags are sold at a reduced price of the contents' original retail value, typically priced at approximately 25 to 50% of the original retail value.
















Participating businesses list surprise bags of surplus foods



Workflow



price

Customers reserve bags at highly discounted



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Customers self pick up during designated time slots



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Key Features of the Platform



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- **Commission-Based Fee:** The platform charges a commission for each bag sold





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 The common approach is to evenly distribute surplus items across all bags, ensuring a similar monetary value. However, this may not always maximize consumer satisfaction







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inventory and surprise bag design

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Our Research Contribution Supports the development of these systems by exploring optimal bag design strategies that ensure long-term profitability and satisfaction



Literature Review


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- Focus on clearance: Yang and Yu (2024) show how surplus food sales reduce waste and boost profits, but may lead to increased consumer-side waste
- Our difference: We explore store reputation and the trade-offs between short-term profits and long-term reputation building in the context of TGTG





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 Our paper is one of the first to examine opaque selling to reduce food waste, and the first to explore the optimal dynamic design of probabilistic goods in this context.











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$$p \cdot n_t - C[\phi_t(\cdot), n_t, Q_t]$$

$$n_t \cdot \int_0^\infty x \phi_t(x) \mathrm{d}x$$

Household waste is not modelled, but also align with distributing more surprise bags and thus





Sequence of events in period t



Payoff realized: $R[\phi_t(\cdot), n_t, Q_t]$

Seller designs food dist.: $\phi_t(x) : \mathbb{R}_+ \to \mathbb{R}_+$ $\begin{array}{c} \xrightarrow{} & \text{Time} \\ & \text{Reputation update} \\ & r_{t+1} = \delta V[\phi_t(\cdot)] + (1 - \delta)r_t \end{array}$

Stage II



Sequence of events in period t



random surplus Q_t

• Stage I: Upon observing the current reputation r_t , the store selects the number of bags to be distributed, n_t , which must satisfy $n_t \leq D(r_t)$, before the realization of



Sequence of events in period t



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• Stage II: After observing the leftover food Q_t , the store determines the food value distribution across bags, represented by the function $\phi_t(\cdot): \mathbb{R}_+ \to \mathbb{R}_+$, based on



Sequence of events in period t



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 $\max_{\pi \in \Pi} \lim_{T \to \infty} \mathbb{E}_{Q_t \sim F} \left[\sum_{t=0}^T \beta^t R \left[\phi_t^{\pi}(\cdot), n_t^{\pi}, Q_t \right] \right]$ subject to $0 \le n_t^{\pi} \le D(r_t)$, $\int_{0}^{\infty} \phi_t^{\pi}(x) \mathrm{d}x = 1,$ $r_{t+1} = \delta V[\phi_t^{\pi}(\cdot)] + (1 - \delta)r_t.$



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$$\circ$$
 (i) $r \mapsto n^{\pi}$

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	тах <i>π</i> ∈П	$\lim_{T\to\infty}$	$\mathbb{E}_{Q_t \sim F}$
subject to $0 \le n_t^{\pi} \le L$			
		$\int_{0}^{\infty} \phi$	$b_t^{\pi}(x) \mathrm{d}x$
		$r_{t+1} =$	$= \delta V[q]$

$$\begin{bmatrix} T \\ \sum_{t=0}^{T} \beta^{t} R \left[\phi_{t}^{\pi}(\cdot), n_{t}^{\pi}, Q_{t} \right] \end{bmatrix}$$
 (Cumulative payer)
$$D(r_{t}),$$
$$x = 1,$$

 $\phi_t^{\pi}(\cdot)] + (1-\delta)r_t.$



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$$\left[\sum_{t=0}^{T} \beta^{t} R\left[\phi_{t}^{\pi}(\cdot), n_{t}^{\pi}, Q_{t}\right]\right]$$

(Upper bound reservation number)



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(Distribution normalization)

 $r_{t+1} = \delta V[\phi_t^{\pi}(\cdot)] + (1-\delta)r_t.$



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 $r_{t+1} = \delta V[\phi_t^{\pi}(\cdot)] + (1-\delta)r_t.$

(Reputation update)

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 $J^*(r) = \max_{n \le D(r)} \left| p \cdot n + \mathbb{E}_Q \left(\max_{\phi(\cdot)} \left[-C[\phi(\cdot), n, Q] + \beta J^* \left(\delta V[\phi(\cdot)] + (1 - \delta)r \right) \right] \right) \right|$



$$J^{*}(r) = \max_{n \le D(r)} \left[p \cdot n + \mathbb{E}_{Q} \left(\max_{\phi(\cdot)} \left[-C[\phi(\cdot)] \right] \right) \right] \right]$$

Proposition $J^*(r)$ is monotonically increasing in r.

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Solving for $\phi^*(\cdot | \ell)$

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Solving for $\phi^*(\cdot | \ell)$

• The conditional optimal food distribution $\phi^*(\cdot | \ell)$ is the optimal solution to



Solving for $\phi^*(\cdot | \ell)$

• The conditional optimal food distribution



$$\int_{0}^{\infty} \psi(x)\phi(x)dx$$

= 1, and $\int_{0}^{\infty} x\phi(x)dx = \ell$.



Solving for $\phi^*(\cdot | \ell)$

The conditional optimal food distribution $\phi^*(\cdot | \ell)$ is the optimal solution to



smallest concave function that is larger than v, by \hat{v} .

subject to $\int_{0}^{\infty} \phi(x) dx = 1$, and $\int_{0}^{\infty} x \phi(x) dx = \ell$.

Definition: denote the upper concave envelope of consumer utility function v, i.e., the



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Proposition The optimal solution $\phi^*(\cdot | \ell)$ is supported by either one or two Dirac points and achieves a population's average utility at $V[\phi^*(\cdot | \ell)] = \hat{v}(\ell).$

 $\int_{0}^{\infty} v(x)\phi(x)dx$ x = 1, and $\int_{0}^{\infty} x\phi(x) dx = \ell$.

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Proposition The optimal solution $\phi^*(\cdot | \ell)$ is supported by either one or two Dirac points and achieves a population's average utility at $V[\phi^*(\cdot | \ell)] = \hat{v}(\ell).$

• When $v(\cdot)$ is concave, evenly distributing is optimal!

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Definition: denote the upper concave envelope of consumer utility function v, i.e., the



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• Base utility function v_0

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- Base utility function v_0

 $v_0(y) = y^{\alpha} \cdot \mathbf{1}_{y \ge 0} - \lambda(-y)^{\alpha} \cdot \mathbf{1}_{y < 0},$



- Base utility function v_0
- $v_0(y) = y^{\alpha} \cdot \mathbf{1}_v$
- $\alpha \in (0,1)$ captures diminishing sensitivity, $\lambda > 1$ captures loss aversion

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 - $^{\circ}$ The posted value of the surprise bag contents p_A

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Ô	Baked Goods		\$1
	4.5 (80)		\$4.
U	Pick up: 10:00 PM - 10:45 PM	Today	
	-		







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 - The price paid for the surprise bag p_R

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$$(x - p_A) + \phi v_0 (x - p_B)$$

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 $\circ v_0(x - p_A)$ captures the reference effects from posted value p_A

$$y \ge 0 - \lambda (-y)^{\alpha} \cdot \mathbf{1}_{y < 0},$$



$$(x - p_A) + \phi v_0 (x - p_B)$$





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- Total utility

 $v(x) = (1 - \phi)v_0$

 $\circ v_0(x - p_A)$ captures the reference effects from posted value p_A $\circ v_0(x - p_B)$ captures the reference effects from price paid p_B

$$y \ge 0 - \lambda (-y)^{\alpha} \cdot \mathbf{1}_{y < 0},$$



$$(x - p_A) + \phi v_0 (x - p_B)$$





Distribution with Non-Concave Utility Function

• When $v(\cdot)$ is non-concave, (at most) two types of bags are needed!



Distribution with Non-Concave Utility Function

• When $v(\cdot)$ is non-concave, (at most) two types of bags are needed!



Note. $\hat{v}(x) = v(x)$ for $x \in \{\underline{x}\} \cup [x_1, x_2] \cup [x_3, \overline{x}]$, and $\hat{v}(x) > v(x)$ for $x \in (\underline{x}, x_1) \cup (x_2, x_3)$. Note that $x_1 > p_B$ and $x_3 > p_A$.

- Consumer utility function v(x) and its upper concave envelope $\hat{v}(x)$



Lookahead Approximation


• Optimize over finite K horizons



• Optimize over finite *K* horizons

$$\begin{split} V^*_t(r) &= \max_{n \leq D(r)} \quad p \cdot n + \mathbb{E}_Q \left[\max_{\ell \geq 0} \{ -C(\ell, 0) \} \right] \\ V^*_0(r) &= 0. \end{split}$$

$(n, Q) + \beta V_{t-1}^* (\delta \hat{v}(\ell) + (1 - \delta)r) \}$ $(1 \le t \le K),$



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• Optimize over finite *K* horizons

$$V_t^*(r) = \max_{n \le D(r)} \quad p \cdot n + \mathbb{E}_Q \left[\max_{\ell \ge 0} \{ -C(\ell, N_0) \} \right]$$
$$V_0^*(r) = 0.$$

• Let $\tilde{\pi}^{(K)} = \{ \tilde{n}^{(K)}, \tilde{\ell}^{(K)} \}$ denote the *K*-LA policy

$(n, Q) + \beta V_{t-1}^* (\delta \hat{v}(\ell) + (1 - \delta)r) \}$ $(1 \le t \le K),$



• Optimize over finite K horizons

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$$V_0^*(r) = 0.$$

• Let $\tilde{\pi}^{(K)} = \{ \tilde{n}^{(K)}, \tilde{\ell}^{(K)} \}$ denote the *K*-LA policy

Proposition Under the 1-LA policy (i.e., myopic policy), the optimal bag number is $\tilde{n}^{(1)}(r) = D(r)$ and the optimal bag value is $\tilde{\ell}^{(1)}(r, Q) = \min\{\bar{x}, Q/D(r)\}$.

$(n, Q) + \beta V_{t-1}^* (\delta \hat{v}(\ell) + (1 - \delta)r)\}$ $(1 \le t \le K),$



Performance Bound of Lookahead Approximation



Performance Bound of Lookahead Approximation

Proposition The revenue gap between the optimal policy and the K-LA policy is bounded by $J^*(r) - \tilde{J}^{(K)}(r) \le \frac{\beta^K p \kappa \delta \zeta}{(1 - (1 - \delta)\beta)(1 - \beta^K)}$.



Performance Bound of Lookahead Approximation

Proposition The revenue gap between the optimal policy and the K-LA policy is bounded by $J^*(r) - \tilde{J}^{(K)}(r) \leq ----$

- **Remark:** the performance bound is tighter when:
 - \circ Time discount factor β is small
 - $^{\circ}$ Weight on new consumers' utility in reputation updating δ is small
 - $^{\circ}$ Number of lookahead periods K is more
 - ° Maximal sensitivity of demand in response to reputation ζ is low
 - $^{\circ}$ Maximal sensitivity of consumers' utility to food value κ is small

 $β^{K} p \kappa \delta \zeta$

$$(1 - (1 - \delta)\beta)(1 - \beta^K)$$





• Deterministic fluid approximation policy π_D



- Deterministic fluid approximation policy π_D
- Replaces random $Q \sim F$ with expectation $\overline{Q} = \mathbb{E}_F[Q]$

Bellman equation is

$$J^{\pi_D}(r) = \max_{\substack{n \le D(r), \ell \ge 0}} pn - C$$

 π_D on $\bar{Q} = \mathbb{E}_F[Q]$

$C(\ell, n, \bar{Q}) + \beta J^{\pi_D} \left[\delta \hat{v}(\ell) + (1 - \delta)r \right]$



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Convex relaxation of single-period payoff (McCormick envelope)

 π_D on $\bar{Q} = \mathbb{E}_F[Q]$

$C(\ell, n, \bar{Q}) + \beta J^{\pi_D} \left[\delta \hat{v}(\ell) + (1 - \delta)r \right]$



- Deterministic fluid approximation policy π_D
- Replaces random $Q \sim F$ with expectation $\overline{Q} = \mathbb{E}_F[Q]$ Bellman equation is

$$J^{\pi_D}(r) = \max_{\substack{n \le D(r), \ell \ge 0}} pn - C(\ell, n, \overline{Q}) + \beta J^{\pi_D} \left[\delta \hat{v}(\ell) + (1 - \delta)r \right]$$

Convex relaxation of single-period payoff (McCormick envelope)

Bellman equation is

 $C(n, \ell, Q) = c(n\ell - Q)^+ \ge c \left[\psi(n, \ell) - Q \right]^+ := \underline{C}(n, \ell, Q)$



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 $J^{MD}(r) = \max pn - \underline{C}(\ell, n, \overline{Q}) + \beta J^{MD} \left[\delta \hat{v}(\ell) + (1 - \delta)r\right]$







 $p \ge c$, then $n^{MD}(r) = D(r)$.

Otherwise, if p < c, we have $n^{MD}(r) =$ the solution to max $p\bar{Q} + (1 - \ell)\bar{n}p$ $\ell \in [0,1]$



Proposition $n^{MD}(r)$ increases in r and $\ell^{MD}(r)$ decreases in r. Specifically, if

$$= D(r) - \left[\ell^{MD}(r)D(r) - \bar{Q}\right]^+, \text{ where } \ell^{MD}(r) \text{ is} \\ + \beta J^{MD} \left[\delta \hat{v}(\ell) + (1 - \delta)r\right].$$



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- When $p \ge c$
 - average bag value based on leftovers
- When p < c
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• The store reduces the number of bags to optimize costs, using the available leftover food more



Performance Bound of Relaxed Policy



Performance Bound of Relaxed Policy

Proposition It holds that $J^{\pi_D} \leq J^*(r) \leq J^M(r) \leq J^{MD}(r)$, and $J^*(r) - J^{\pi_D}(r) \leq J^{MD}(r) - J^{\pi_D}(r) \leq \frac{c}{1-\beta} \cdot \left[\frac{\sigma}{2} + \left(\sqrt{D(r)} - \sqrt{\bar{Q}/\bar{x}}\right)^2\right]$



Performance Bound of Relaxed Policy

Remark: the performance bound is tighter when

- \circ Smaller time discount factor β
- Lower supplementary costs *C*
- $^{\circ}$ Smaller standard deviation σ
- ° Aligning \overline{Q} with xD(r)

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Proposition Under the optimal policy with deterministic leftover, the steadystate bag value converges to ℓ^* , corresponding to the store's steady-state reputation $r^* = \hat{v}(\ell^*)$ and bag number $n^* = D(r^*) = D[\hat{v}(\ell^*)]$. The steady-state bag value is the unique solution to

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- Implication: Stores do not need to maintain a *perfect* rating
- Each store reaches a different long-term reputation level, with key influencing factors:
 - Cost structure
 - Consumer preferences
 - Demand dynamics
 - Reputation update mechanism

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Numerical Experiments



Numerical Experiments

- Experiment setup
 - We assume a simple logstic utility function with one reference point, given by $v(x) = \frac{1}{1 + e^{-10(x-0.5)}}.$

• Its upper concave
envelope can be
expressed as
$$\hat{v}(x) = \begin{cases} 1.25x & \text{if } x \in [0,0.676];\\ \frac{1}{1+e^{-10(x-0.5)}} & \text{if } x \in (0.676,1]. \end{cases}$$



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Optimal policy

(c) Number of support points of $\phi^*(\cdot | \ell^*(r, Q))$

(d) Supplementary at optimality $n^*(r)\ell^*(r,Q) - Q$



Policy Comparison: Revenue

deterministic approximation policy π_D , and iv) the naive policy π_N .

Average revenues under different policies

Parameters $(c, \delta), Q \sim F$	Optimal	2-LA	DFA	Naive
$(5, 0.3), Q \sim U[0, 12]$	844.12 ± 13.91	841.82 ± 14.39	793.92 ± 10.44	787.78 ± 25.27
$(5, 0.6), Q \sim U[0, 12]$	931.70 ± 14.03	921.89 ± 14.07	870.41 ± 9.04	867.68 ± 27.23
$(10, 0.3), Q \sim U[0, 12]$	827.59 ± 21.78	826.44 ± 21.89	796.61 ± 23.44	794.27 ± 32.37
$(10, 0.6), Q \sim U[0, 12]$	910.14 ± 18.10	900.15 ± 18.10	858.10 ± 19.05	880.94 ± 25.72
$(5, 0.3), Q \sim U[3, 9]$	850.48 ± 10.77	849.39 ± 11.20	829.41 ± 7.32	849.96 ± 11.43
$(5, 0.6), Q \sim U[3, 9]$	921.94 ± 7.18	891.93 ± 7.20	916.91 ± 5.87	890.39 ± 7.64
$(10, 0.3), Q \sim U[3, 9]$	856.73 ± 8.80	855.63 ± 8.76	801.22 ± 10.99	859.46 ± 8.78
$(10, 0.6), Q \sim U[3, 9]$	936.56 ± 9.60	926.56 ± 9.60	889.64 ± 13.54	909.09 ± 9.61

Note: \pm indicates the half-width of the 95% confidence interval for the estimated means of each metric.

• We compare four policies: i) the optimal policy π^* , ii) the 2-LA policy $\pi^{(2)}$, iii) the





Policy Comparison: Waste

deterministic approximation policy π_D , and iv) the naive policy π_N .

Average in-store waste under different policies





• We compare four policies: i) the optimal policy π^* , ii) the 2-LA policy $\pi^{(2)}$, iii) the

	2-LA	DFA	Naive
)7	6.59 ± 2.08	22.82 ± 2.72	8.15 ± 1.66
_4	5.19 ± 2.14	22.12 ± 2.27	8.20 ± 1.66
)3	8.09 ± 2.01	24.36 ± 3.20	9.06 ± 1.60
76	6.83 ± 1.76	22.74 ± 3.23	8.56 ± 1.26
9	6.94 ± 1.19	14.75 ± 1.74	6.77 ± 1.19
$_{-}7$	6.65 ± 1.17	13.99 ± 1.26	6.62 ± 1.17
)()	7.60 ± 0.93	15.94 ± 1.54	6.77 ± 0.90
B O	6.26 ± 1.30	15.85 ± 1.41	5.87 ± 1.33

Note: \pm indicates the half-width of the 95% confidence interval for the estimated means of each metric.



Numerical Experiments: System Convergence





Right: High c/p ratio



Summary




Infinite-Horizon Model

Captures reputation's dynamic impact on demand through a two-stage decision process.



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- Optimal Bag Distribution
 - One bag type if consumer utility is concave concave envelope.

• One bag type if consumer utility is concave; otherwise up to two types identified via an upper



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Future Directions

End-to-end management/ Information disclosure / Pricing effects /...

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Thank you for your attention!

Questions and comments are appreciated! Email: hansheng.jiang@rotman.utoronto.ca

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